



TECHNICAL PAPER

STANDARDIZED UXO DEMONSTRATION SITES

SHAW ENVIRONMENTAL, INC. – UXO MAPPER G856 MAGNETOMETER/ PUSHCART - MOGULS SCORING RECORD NO. 594



The UXO Mapper G856 Magnetometer in the pushcart platform is shown being demonstrated by Shaw Environmental, Inc. at Yuma Proving Ground, Arizona.

The UXO Mapper G856 Magnetometer in the pushcart platform was demonstrated by Shaw Environmental, Inc. at the Yuma Proving Ground Standardized Demonstration Site's Moguls Area. This technical paper contains the results of that demonstration. This is a reference document only and does not serve as an endorsement of the demonstrator's product by the US Army or the Standardized UXO Technology Sites Program.

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Technologies under development for the detection and discrimination of unexploded ordnance (UXO) require testing so that their performance can be characterized. To that end, Standardized Test Sites have been developed at Aberdeen Proving Ground (APG), Maryland and Yuma Proving Ground (YPG), Arizona. These test sites provide a diversity of geology, climate, terrain, and weather as well as diversity in ordnance and clutter. Testing at these sites is independently administered and analyzed by the government for the purposes of characterizing technologies, tracking performance with system development, comparing performance of different systems, and comparing performance in different environments.

The Standardized UXO Technology Demonstration Site Program is a multi-agency program spearheaded by the U.S. Army Environmental Center (USAEC). The U.S. Army Aberdeen Test Center (ATC) and the U.S. Army Corps of Engineers Engineering Research and Development Center (ERDC) provide programmatic support. The program is being funded and supported by the Environmental Security Technology Certification Program (ESTCP), the Strategic Environmental Research and Development Program (SERDP) and the Army Environmental Quality Technology Program (EQT).

DEMONSTRATOR'S SYSTEM AND DATA PROCESSING DESCRIPTION

Shaw's geophysical mapping technology is an engineered combination of off-the-shelf geophysical sensors, innovative navigation technologies, a flexible/configurable deployment system, and customized data acquisition software. The geophysical sensor selected for this demonstration is an array of magnetometers. The Shaw UXO Mapper has both hardware and software components: Leica TSP1100 Robotic Total Station (RTS) for in-the-tree and open-area navigation, crossbow 3-axis gyro system, Shaw's composite material cart-deployment system, off-the-shelf magnetic (G858) sensors, software for data acquisition system for sensor, navigation and gyro data collection, software to achieve robust navigation and sensor time-base synchronization, and software to implement real-time telemetry and data merging.

For navigation, the Shaw UXO Mapper uses RTS technology. The Leica TSP1100 RTS is a motorized robotic total station that uses automatic target recognition to track the location of the prism and has a highly accurate distance/azimuth measurement system to produce +5 mm +2 ppm accuracy which translates to 0.25 inches (3D) at distances of up to 1400 feet.

The Shaw UXO Mapper has three software components. First, customized RTS firmware is used to track the roving prism. Developed specifically for Shaw's UXO mapping applications, this firmware allows for rapid collection

of data to 4 hertz and outputs solutions to the base station and rover units. The firmware enables the user to optimize prism-tracking parameters for rapid recovery of lock if obstructed by trees during a survey. Second, Shaw's data control software determines precise time synchronization between the RTS and sensor time bases, ensuring accurate collection of all data. Third, Shaw's software for data merging accommodates various sensor navigation geometries used during data collection and provides a robust framework to spatially configure sensors relative to each other and with respect to the prism location. Additionally, this software allows RTS and sensor data to be merged in either a straightforward interpolation mode (for open areas) or in hybrid switching mode that alternates to "dead reckoning" for the brief periods when the RTS is obstructed in the woods.

PERFORMANCE SUMMARY

Results for the Moguls test broken out by size, depth and nonstandard ordnance are presented in table below. Results by size and depth include both standard and nonstandard ordnance. The results by size show how well the demonstrator did at detecting/discriminating ordnance of a certain caliber range. The results are relative to the number of ordnance items employed. Depth is measured from the geometric center of anomalies.

The Response Stage results are derived from the list of anomalies above the demonstrator-provided noise level. The results for the Discrimination Stage are derived from the demonstrator's recommended threshold for optimizing UXO field cleanup by minimizing false digs and maximizing ordnance recovery. The lower 90 percent confidence limit on probability of detection and P_{fp} was calculated assuming that the number of detections and false positives are binomially distributed random variables. All results have been rounded to protect the ground truth. However, lower confidence limits were calculated using actual results.

The overall ground truth is composed of ferrous and non-ferrous anomalies. Due to limitations of the magnetometer, the non-ferrous items cannot be detected. Therefore, the summary presented in the "Ferrous Only" table exhibits results based on the subset of the ground truth that is solely the ferrous anomalies. The second table exhibits results based on the full ground truth. The response stage noise level and recommended discrimination stage threshold values are provided by the demonstrator.

SUMMARY OF MOGUL RESULTS (FERROUS ONLY)

Metric	Overall	Standard	Nonstandard	By Size			By Depth, m		
				Small	Medium	Large	< 0.3	0.3 to <1	>= 1
RESPONSE STAGE									
P _d	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
P _d Low 90% Conf	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
P _d Upper 90% Conf	0.04	0.07	0.05	0.08	0.06	0.13	0.06	0.07	0.28
P _{fa}	0.05	-	-	-	-	-	0.05	0.05	0.00
P _{fa} Low 90% Conf	0.03	-	-	-	-	-	0.02	0.01	0.00
P _{fa} Upper 90% Conf	0.07	-	-	-	-	-	0.07	0.13	0.08
BAR	0.55	-	-	-	-	-	-	-	-
DISCRIMINATION STAGE									
P _d	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
P _d Low 90% Conf	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
P _d Upper 90% Conf	0.02	0.04	0.05	0.05	0.005	0.13	0.04	0.07	0.28
P _{fa}	0.05	-	-	-	-	-	0.05	0.05	0.00
P _{fa} Low 90% Conf	0.01	-	-	-	-	-	0.01	0.00	0.00
P _{fa} Upper 90% Conf	0.05	-	-	-	-	-	0.05	0.10	0.08
BAR	0.15	-	-	-	-	-	-	-	-

Response Stage Noise Level: -7.2

Recommended Discrimination Stage Threshold: 6.90

SUMMARY OF MOGUL RESULTS (FULL GROUND TRUTH)

Metric	Overall	Standard	Nonstandard	By Size			By Depth, m		
				Small	Medium	Large	< 0.3	0.3 to <1	>= 1
RESPONSE STAGE									
P _d	0.05	0.05	0.00	0.05	0.00	0.00	0.05	0.00	0.00
P _d Low 90% Conf	0.01	0.01	0.00	0.02	0.00	0.00	0.01	0.00	0.00
P _d Upper 90% Conf	0.06	0.07	0.08	0.10	0.06	0.13	0.09	0.06	0.28
P _{fa}	0.05	-	-	-	-	-	0.05	0.05	0.00
P _{fa} Low 90% Conf	0.03	-	-	-	-	-	0.02	0.01	0.00
P _{fa} Upper 90% Conf	0.07	-	-	-	-	-	0.07	0.13	0.08
BAR	0.55	-	-	-	-	-	-	-	-
DISCRIMINATION STAGE									
P _d	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
P _d Low 90% Conf	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
P _d Upper 90% Conf	0.03	0.05	0.05	0.05	0.00	0.13	0.05	0.08	0.28
P _{fa}	0.05	-	-	-	-	-	0.05	0.05	0.00
P _{fa} Low 90% Conf	0.01	-	-	-	-	-	0.01	0.00	0.00
P _{fa} Upper 90% Conf	0.05	-	-	-	-	-	0.05	0.10	0.08
BAR	0.15	-	-	-	-	-	-	-	-

Response Stage Noise Level: -7.2

Recommended Discrimination Stage Threshold: 6.90

Note: The recommended discrimination stage threshold values are provided by the demonstrator.

To view the full Scoring Record for this demonstration and for all other demonstrations conducted at the Aberdeen and Yuma Proving Grounds in support of the Standardized UXO Technology Demonstration Sites Program please visit our Web site at: www.uxotestsites.org.

